



LARGE: A Length-Aggregation-based Grid Structure for Line Density Visualization





Tsz Nam Chan Shenzhen University edisonchan@szu.edu.cn

Bojian Zhu Hong Kong Baptist University csbjzhu@comp.hkbu.edu.hk

Dingming Wu Shenzhen University dingming@szu.edu.cn

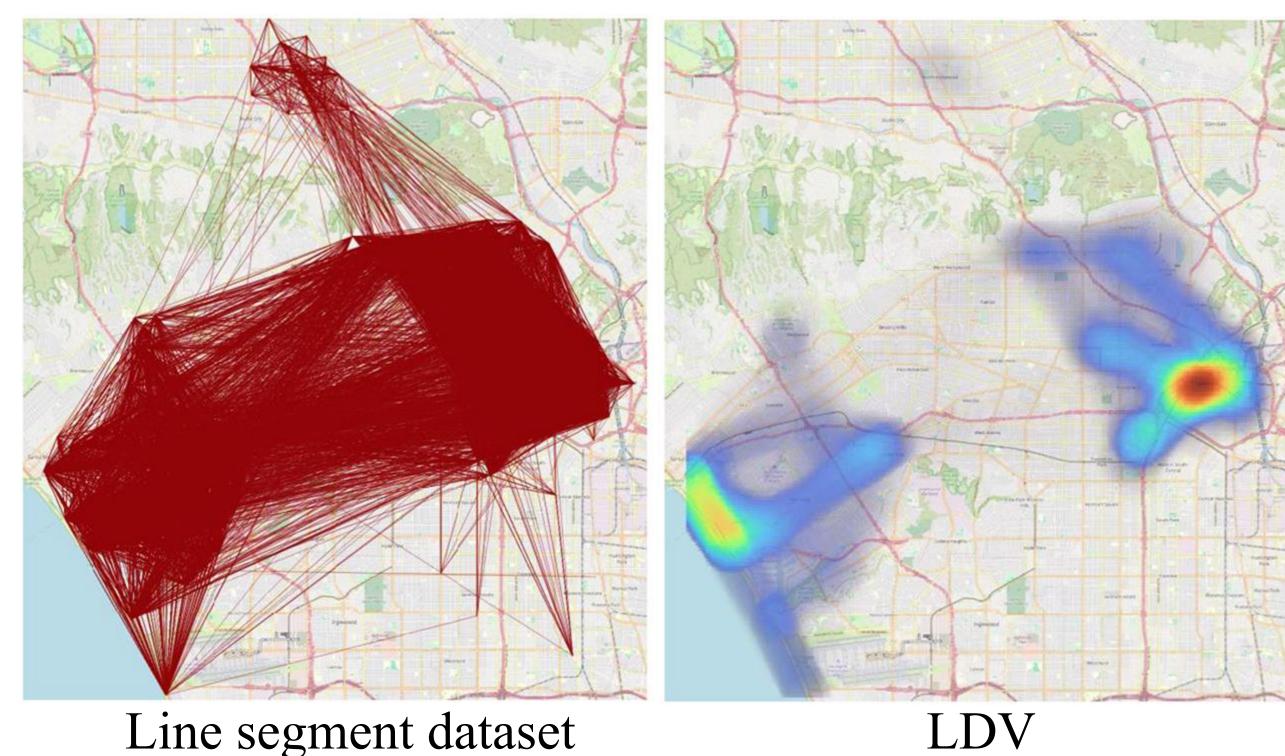
Yun Peng Guangzhou University yunpeng@gzhu.edu.cn

Leong Hou U University of Macau ryanlhu@um.edu.mo





What is Line Density Visualization (LDV)?



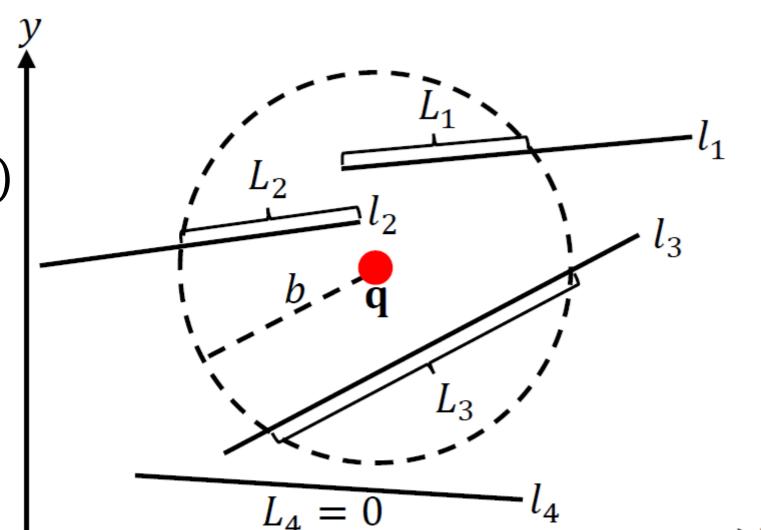
LDV

Applications: (i) traffic flow analysis and (ii) mobility analysis Software packages that support LDV: ArcGIS and QGIS

Given a set of line segments with size n, generating a $X \times Y$ -resolution LDV involves the computation of the line density value $\mathcal{L}(\mathbf{q})$ for each pixel q.

$$\mathcal{L}(\mathbf{q}) = \frac{1}{\pi b^2} \sum_{i=1}^n L_i$$

where L_i denotes the length of line segment l_i that is within the range b of **q**.



Weakness of LDV:

- (1) LDV takes O(XYn) time, which cannot be scalable to a large resolution size and a large number of line segments. ③
- (2) Commonly used software packages, ArcGIS and QGIS, merely adopt the naïve implementation, which cannot handle large-scale datasets. ©

Approximate LDV

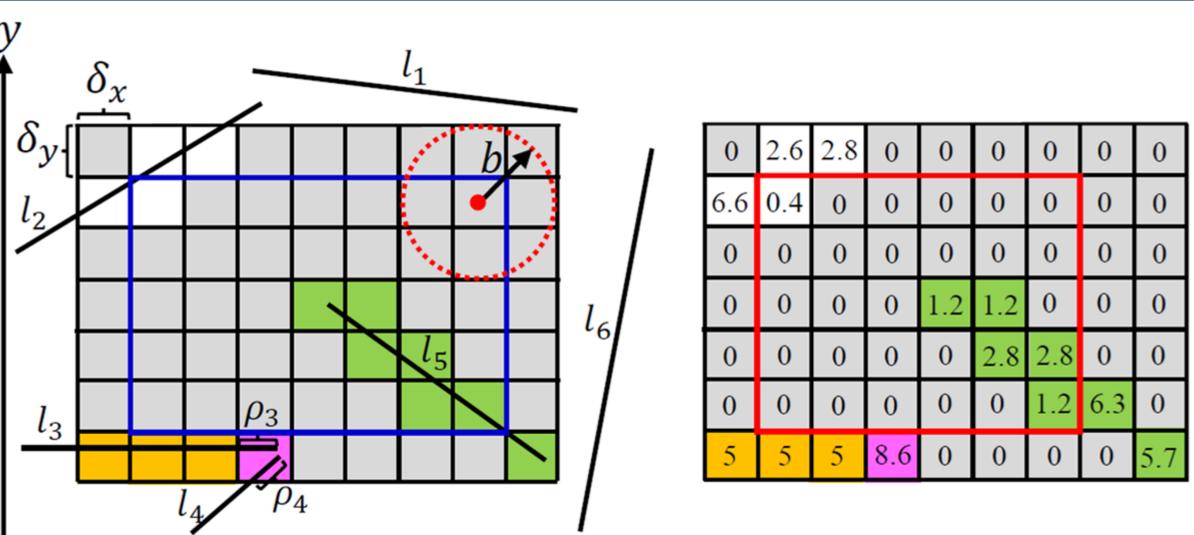
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 ϵ LDV: Given a relative error ϵ , we need to compute $A(\mathbf{q})$ for each pixel \mathbf{q} so that

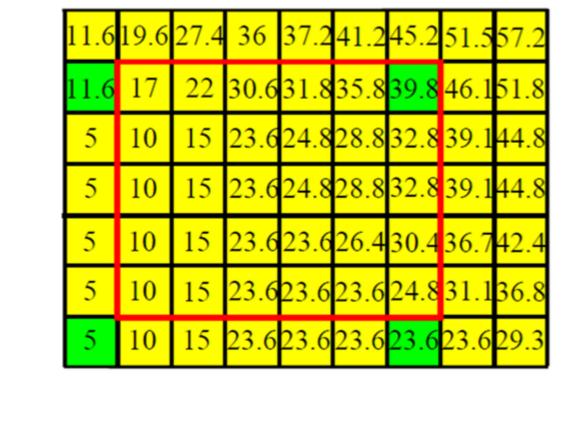
$$(1 - \epsilon)\mathcal{L}(\mathbf{q}) \le A(\mathbf{q}) \le (1 + \epsilon)\mathcal{L}(\mathbf{q})$$

 τ LDV: Given a set of *D* thresholds, $\tau_1, \tau_2, ..., \tau_D$, we need to classify $\mathcal{L}(\mathbf{q})$ to be different color levels $\mathcal{C}(\mathbf{q})$

$$C(\mathbf{q}) = \begin{cases} 0 & \text{if } \mathcal{L}(\mathbf{q}) < \tau_1 \\ 1 & \text{if } \tau_1 \le \mathcal{L}(\mathbf{q}) < \tau_2 \\ \vdots & & \\ D & \text{if } \mathcal{L}(\mathbf{q}) \ge \tau_D \end{cases}$$



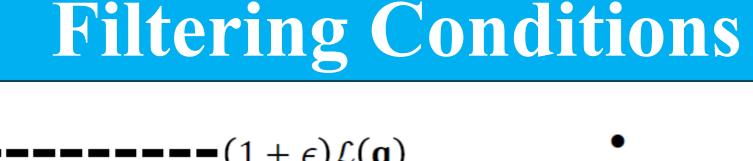
Find the accumulative length for each entry.

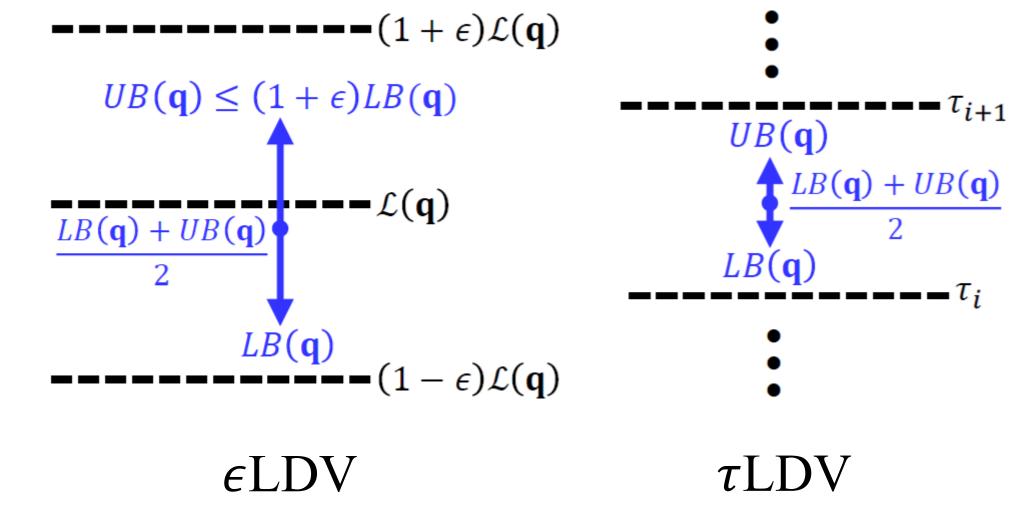


Construct LARGE.

Bound Functions (based on LARGE)

$LB_a(\mathbf{q})$ $UB_a(\mathbf{q})$ $UB_{\square}(\mathbf{q})$ $LB_{\square}(\mathbf{q})$ O(1) time $O(\min(X, Y))$ time

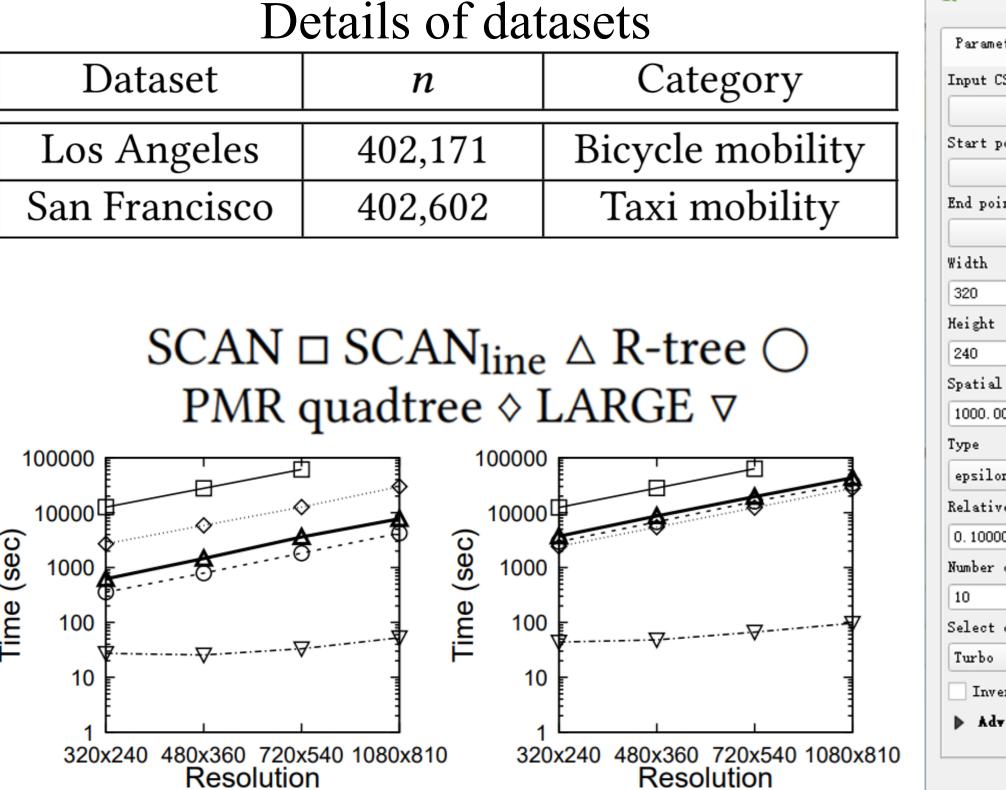


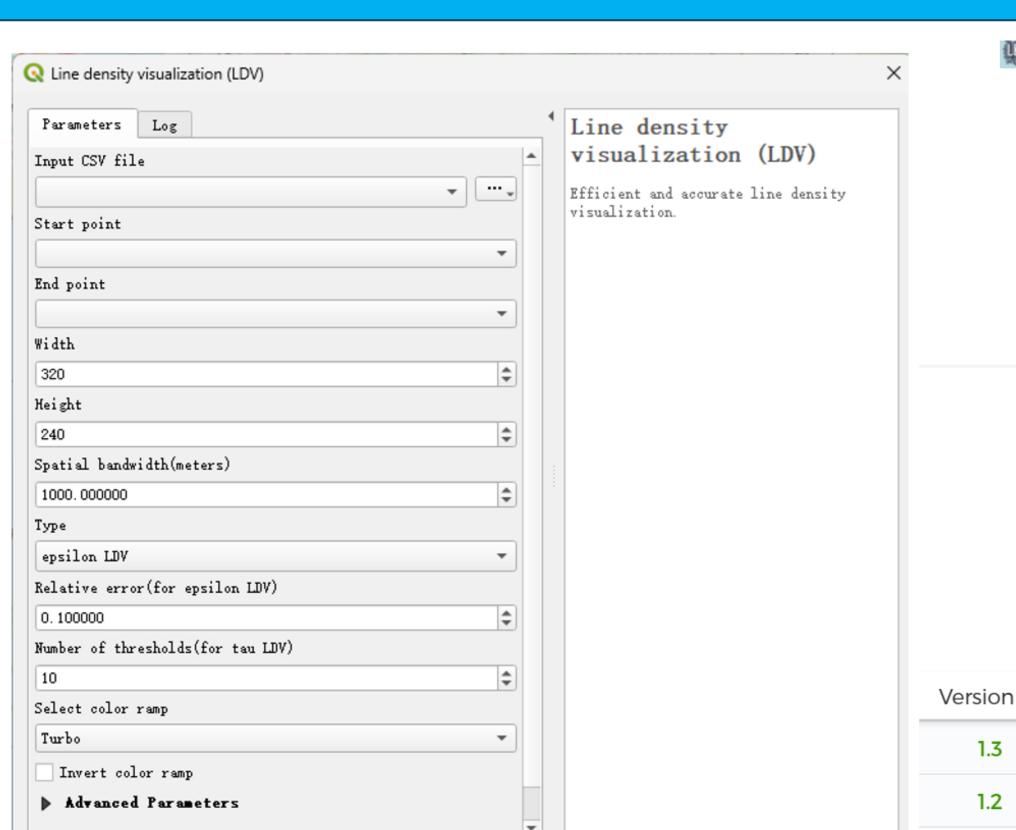


Efficiency Results

User Interface

Number of Users





0%

Advanced - Run as Batch Process...

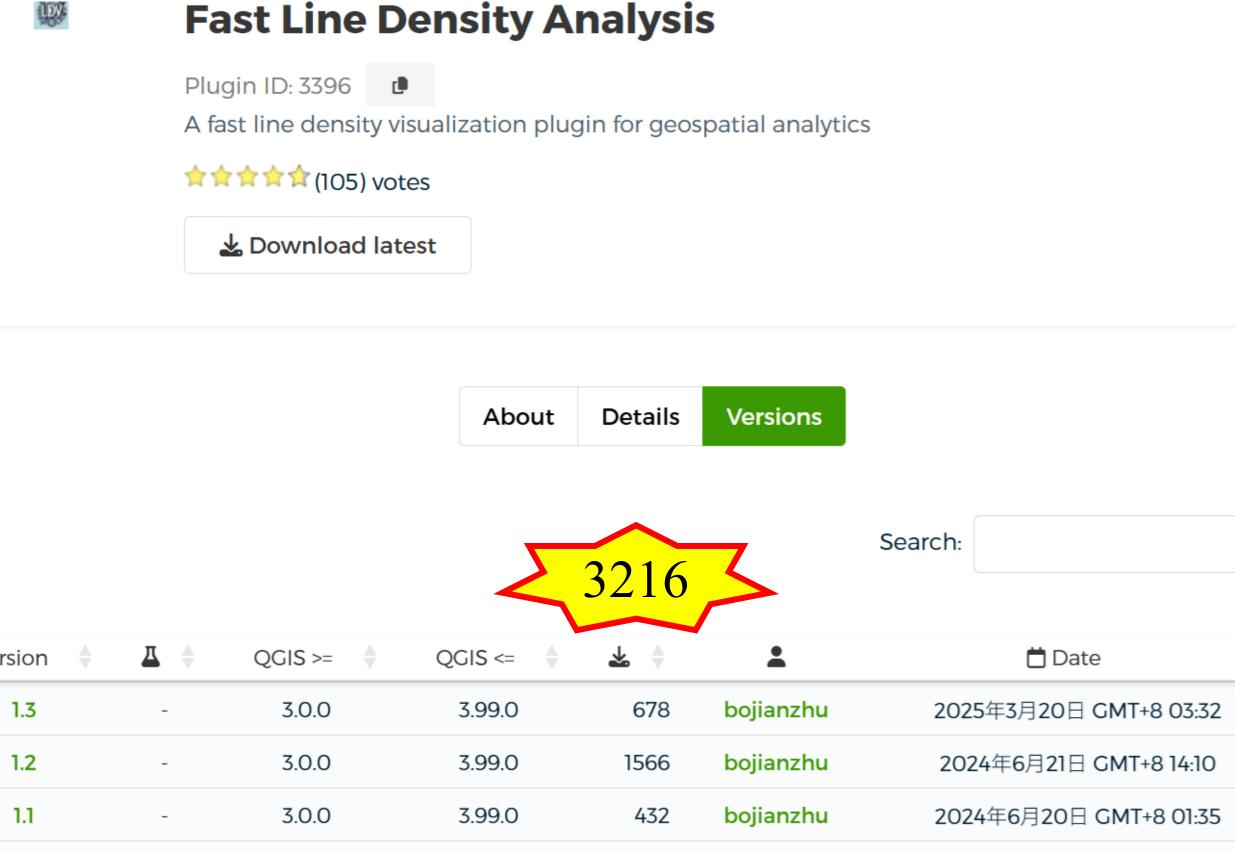
Cancel

帮助

关闭

Run

1.0



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bojianzhu

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